

## EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	323	(73/865.4 600/595 901/1 901/9 901/10 901/46 414/1 414/2).ccls.	US-PGPUB	OR	ON	2007/07/19 12:31
L2	8	(73/865.4 600/595 901/1 901/9 901/10 901/46 414/1 414/2).ccls.	FPRS	OR	ON	2007/07/19 12:34
L3	203	(73/865.4 600/595 901/1 901/9 901/10 901/46 414/1 414/2).ccls.	EPO	OR	ON	2007/07/19 12:35
L4	480	(73/865.4 600/595 901/1 901/9 901/10 901/46 414/1 414/2).ccls.	JPO	OR	ON	2007/07/19 12:36
L5	2285	(73/865.4 600/595 901/1 901/9 901/10 901/46 414/1 414/2).ccls.	USPAT	OR	ON	2007/07/19 14:14
L6	0	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder) with (((angular angle angularly) near (position positioning positioned)) near10 ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint)))	IBM_TDB	OR	ON	2007/07/19 14:33
L7	1	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder) with (((angular angle angularly) near (position positioning positioned)) near10 ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint)))	US-PGPUB	OR	ON	2007/07/19 14:28
L8	0	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder) with (((angular angle angularly) near (position positioning positioned)) near10 ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint)))	FPRS	OR	ON	2007/07/19 14:28

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L9	0	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder) with (((angular angle angularly) near (position positioning positioned)) near10 ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint)))	EPO	OR	ON	2007/07/19 14:28
L10	0	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder) with (((angular angle angularly) near (position positioning positioned)) near10 ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint)))	JPO	OR	ON	2007/07/19 14:28
L11	0	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder) with (((angular angle angularly) near (position positioning positioned)) near10 ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint)))	DERWENT	OR	ON	2007/07/19 14:31
L12	0	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder) with (((angular angle angularly) near (position positioning positioned)) near10 ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint)))	USOCR	OR	ON	2007/07/19 14:31

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L13	0	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder) with (((angular angle angularly) near (position positioning positioned)) near10 ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint)))	USPAT	OR	ON	2007/07/19 14:31
L14	0	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) with (((((angular angle angularly) near (position positioning positioned movement moved move moving)) (posture postured posturing)) near10 ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint)))	IBM_TDB	OR	ON	2007/07/19 14:38
L15	1	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) with (((((angular angle angularly) near (position positioning positioned movement moved move moving)) (posture postured posturing)) near10 ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint)))	US-PGPUB	OR	ON	2007/07/19 14:38

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L16	0	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) with (((angular angle angularly) near (position positioning positioned movement moved move moving)) (posture postured posturing)) near10 ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint)))	FPRS	OR	ON	2007/07/19 14:38
L17	0	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) with (((angular angle angularly) near (position positioning positioned movement moved move moving)) (posture postured posturing)) near10 ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint)))	EPO	OR	ON	2007/07/19 14:38
L18	0	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) with (((angular angle angularly) near (position positioning positioned movement moved move moving)) (posture postured posturing)) near10 ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint)))	JPO	OR	ON	2007/07/19 14:38

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L19	0	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) with (((angular angle angularly) near (position positioning positioned movement moved move moving)) (posture postured posturing)) near10 ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint)))	DERWENT	OR	ON	2007/07/19 14:39
L20	0	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) with (((angular angle angularly) near (position positioning positioned movement moved move moving)) (posture postured posturing)) near10 ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint)))	USOCR	OR	ON	2007/07/19 14:39
L21	0	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) with (((angular angle angularly) near (position positioning positioned movement moved move moving)) (posture postured posturing)) near10 ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint)))	USPAT	OR	ON	2007/07/19 14:40

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L22	0	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) near10 (((angular angle angularly) near (position positioning positioned movement moved move moving)) (posture postured posturing))) and ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint) and ((rigid rigidly) near5 (link linking linled linker))	IBM_TDB	OR	ON	2007/07/19 14:47
L23	1	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) near10 (((angular angle angularly) near (position positioning positioned movement moved move moving)) (posture postured posturing))) and ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint) and ((rigid rigidly) near5 (link linking linled linker))	US-PGPUB	OR	ON	2007/07/19 14:47
L24	0	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) near10 (((angular angle angularly) near (position positioning positioned movement moved move moving)) (posture postured posturing))) and ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint) and ((rigid rigidly) near5 (link linking linled linker))	FPRS	OR	ON	2007/07/19 14:48

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L25	1	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) near10 (((angular angle angularly) near (position positioning positioned movement moved move moving)) (posture postured posturing))) and ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint) and ((rigid rigidly) near5 (link linking linled linker))	EPO	OR	ON	2007/07/19 14:49
L26	0	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) near10 (((angular angle angularly) near (position positioning positioned movement moved move moving)) (posture postured posturing))) and ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint) and ((rigid rigidly) near5 (link linking linled linker))	JPO	OR	ON	2007/07/19 14:49
L27	1	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) near10 (((angular angle angularly) near (position positioning positioned movement moved move moving)) (posture postured posturing))) and ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint) and ((rigid rigidly) near5 (link linking linled linker))	DERWENT	OR	ON	2007/07/19 14:49

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L28	0	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) near10 (((angular angle angularly) near (position positioning positioned movement moved move moving)) (posture postured posturing)) and ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint) and ((rigid rigidly) near5 (link linking linled linker))	USOCR	OR	ON	2007/07/19 14:50
L29	0	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) near10 (((angular angle angularly) near (position positioning positioned movement moved move moving)) (posture postured posturing)) and ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint) and ((rigid rigidly) near5 (link linking linled linker))	USPAT	OR	ON	2007/07/19 14:50
L30	0	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) near10 (((angular angle angularly) near (position positioning positioned movement moved move moving)) (posture postured posturing)) and ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint)	IBM_TDB	OR	ON	2007/07/19 14:50

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L31	6	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) near10 (((angular angle angularly) near (position positioning positioned movement moved move moving)) (posture postured posturing))) and ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint)	US-PGPUB	OR	ON	2007/07/19 15:08
L32	0	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) near10 (((angular angle angularly) near (position positioning positioned movement moved move moving)) (posture postured posturing))) and ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint)	FPRS	OR	ON	2007/07/19 14:57
L33	1	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) near10 (((angular angle angularly) near (position positioning positioned movement moved move moving)) (posture postured posturing))) and ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint)	EPO	OR	ON	2007/07/19 14:57

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L34	0	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) near10 (((angular angle angularly) near (position positioning positioned movement moved move moving)) (posture postured posturing))) and ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint)	JPO	OR	ON	2007/07/19 14:57
L35	1	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) near10 (((angular angle angularly) near (position positioning positioned movement moved move moving)) (posture postured posturing))) and ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint)	DERWENT	OR	ON	2007/07/19 14:57
L36	0	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) near10 (((angular angle angularly) near (position positioning positioned movement moved move moving)) (posture postured posturing))) and ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint)	USOCR	OR	ON	2007/07/19 14:57